Torsional Alfvén waves in a rotating spherical shell: transmission and reflection in the Earth's outer core

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Torsional oscillations from numerical simulations of the geodynamo



Pm=0.1, Ro=5 10⁻⁴, Le=2 10⁻³, A=0.27

See also Aubert, 2018: Pm=, Ro=2.4 10⁻⁴, Le=2.2 10⁻³, A=0.11

Schaeffer & al., 2017

Torsional Alfvén waves



Torsional waves consist of geostrophic motions coupled by the magnetic field in the Earth's fluid outer core

Six year oscillation in length-of-day



Torsional Alfvén modes of periods ~ 6 years and less

SSA reconstruction, pair of eigen modes



Not an harmonic of the solar cycle

SILSO graphics (http://sidc.be/silso) Royal Observatory of Belgium 2018 March 1

Coupling between external magnetic fields and torsional waves

- External fields of periods 11 years (dipole), 1 year (axial quadrupole) and 6 months (axial dipole).
- Induced field, solid core approximation: B_r=0 at the core-mantle boundary (as a result of
 electrical currents in a magnetic diffusive layer at the core surface).
- Previous studies (Gédéon Légaut thesis, 2005): 11 years component interacting with torsional waves, assuming the period of the main mode is ~60 years.
- Axial part of the dipole: ineffective; weak waves propagating inwards in the fluid core from the equator.
- *Gillet & al., 2010*: revised period of the main mode, 6 years.
- What induced field in the Earth's fluid core with period 1 year, implications for models of mantle electrical conductivity ? Emission of torsional waves with 1 year period? Auspicious quadrupolar geometry.
- But : attenuation across the mantle.

The 'mantle filter'



Trade-off between geometric attenuation and the impact of the electrical conductivity of the mantle (*Jault, 2015*)

Electromagnetic sounding



Transfer function for European observatories assuming the Earth's core can be treated as a solid (*Olsen, 1999*)

1 year, 6 months

Domain of existence of torsional Alfvén waves

Torsional waves present when:

$$\lambda = \frac{V_A}{\Omega r_c} = \frac{B}{\sqrt{\rho\mu}\Omega r_c} \ll 1$$

Frequency:

$$\omega \sim \frac{V_A}{r_c} = \lambda \Omega$$

Standard equations developed in a full sphere for:

$$\left(\frac{\nu}{\Omega\cos\theta}\right)^{1/2} \ll \left(\frac{\eta}{\omega}\right)^{1/2}, \qquad P_m\left(\frac{\omega}{\Omega}\right) \ll \cos\theta$$

(θ colatitude)

The hydromagnetic assumption

• Stewartson's jump condition through the boundary layer (with *B*_{0,r} directed towards the fluid interior) for the zonal toroidal components:

$$\left[P_m^{1/2}u_\phi - \frac{b_\phi}{\sqrt{\mu\rho}}\right] = 0, \quad P_m = \frac{\nu}{\eta}$$

- when it is not satisfied: emission of Alfvén waves to erase the discontinuity
- application: boundary condition for torsional waves at the Earth's core equator
- In the λ≪1 framework, assumption: velocity shear in the direction parallel to the rotation axis forbidden ⇒ inhibition of the emission of Alfvén waves and construction of a magnetic diffusive layer away from the equator

Torsional wave equation

High frequency approximation

$$\zeta(s,t) = \exp(-i\omega t)\zeta_G(s), \qquad \omega^2 \zeta_G(s) = -\frac{1}{m} \frac{\mathrm{d}}{\mathrm{d}s} \left(m V_A^2 \frac{\mathrm{d}\zeta_G}{\mathrm{d}s} \right) \qquad m = s^3 h$$

- Same equation for long gravity waves (of small height) in a channel of slowly varying width and depth
- George Green (1837): high frequency approximations to the solution, first instance of the method later known as the WKB method (two-lengthscale expansion)
- approximated solution away from the boundaries:

$$\zeta_G(s) = \frac{C}{\sqrt{mV_A}} \exp\left[i\int_{s_0}^s \frac{\omega}{V_A} ds - i\omega t\right]$$

high frequency approximation valid where:

$$\frac{1}{m}\frac{\mathrm{d}m}{\mathrm{d}s} \ll \frac{\omega}{V_A}, \quad \frac{\mathrm{d}V_A}{\mathrm{d}s} \ll \omega$$

Equatorial (V_A constant) solution

Limit cases: Neumann or Dirichlet boundary conditions

Boundary condition (at the equator):
$$\frac{\mathrm{d}\zeta_G}{\mathrm{d}s}\Big|_{s=1} = 0$$
 $(\frac{\nu}{\eta} = P_m = 0)$ or $\zeta_G(1) = 0$ $(P_m = \infty)$

Choice of unit: $V_A(1) \equiv 1$

$$h = \sqrt{2x}$$
 $x = 1 - s, \quad -\omega^2 \zeta_G(x) = \frac{1}{\sqrt{x}} \frac{\mathrm{d}}{\mathrm{d}x} \left(\sqrt{x} \frac{\mathrm{d}\zeta_G(x)}{\mathrm{d}x} \right)$

Two independent solutions: $x^{1/4}J_{-1/4}(\omega x), x^{1/4}J_{1/4}(\omega x)$

For
$$\left. \frac{\mathrm{d}\zeta_G}{\mathrm{d}s} \right|_{s=1} = 0$$

 $\zeta_G(s) = C_{\mathrm{III}}(1-s)^{1/4} J_{-1/4}(\omega(1-s))$

Matching between the WKB and equatorial solutions

In the limit of high frequency:

$$\zeta_G(s) = C_{\text{III}} \left(\frac{2}{\pi}\right)^{1/2} \omega^{-1/2} (1-s)^{-1/4} \cos\left[\omega(1-s) - \frac{\pi}{8}\right] + O\left(\omega^{-3/2}\right)^{1/2} \omega^{-1/2} \left(1-s\right)^{-1/4} \cos\left[\omega(1-s) - \frac{\pi}{8}\right] + O\left(\omega^{-3/2}\right)^{1/2} \omega^{-1/2} \left(1-s\right)^{1/2} \left(1$$

Matching with the WKB solution in the interior (as in *Maffei & Jackson, 2016*):

$$\zeta_G(s) = \frac{C_{\text{II}}}{\sqrt{mV_A}} \cos(\omega\tau(s) + \phi_0), \qquad \tau(s) = \int_s^1 \frac{\mathrm{d}s}{V_A} = 1 - s, \qquad \phi_0 = -\frac{\pi}{8}$$

On the axis (Mound & Buffett, 2007):

$$\frac{\partial \zeta_G}{\partial s}\Big|_{s=0} = 0 \qquad \qquad \zeta_G(s) = C_I \frac{J_1\left(\omega s/V_A(0)\right)}{s} \qquad \qquad J_1(\omega s) \sim \sqrt{\frac{2V_A(0)}{\pi \omega s}} \cos\left[-\frac{\omega s}{V_A(0)} + \frac{3\pi}{4}\right]$$

 \Rightarrow quantification of the eigenvalues:

Example:

$$\forall s, \quad V_A(s) = 1$$
 $\omega(1-s) - \frac{\pi}{8} = -\omega s + \frac{3\pi}{4} + n\pi, \quad \omega_n = \left(n + \frac{7}{8}\right)\pi$

The second family of normal modes

For
$$\zeta_G(1) = 0$$

$$\zeta_G(s) = C_{\rm III}(1-s)^{1/4} J_{1/4}(\omega(1-s))$$

In the limit of high frequency:

$$\zeta_G(s) \sim C_{\text{III}} \left(\frac{2}{\pi}\right)^{1/2} \omega^{-1/2} (1-s)^{-1/4} \cos\left[\omega(1-s) - \frac{3\pi}{8}\right]$$

 $\omega_n = \left(n + \frac{9}{8}\right) \pi$

Asymptotic matching in the equatorial region



Illustration with a non-uniform Alfvén velocity from Roberts & Aurnou (2012)



 ω_n depends of the magnetic field model, only through the travel time τ

Finite magnetic Prandtl number

1-D theory: Alfvén waves across a plane slab

 $0 < P_m < \infty$

 $\frac{\partial^2 u}{\partial x^2} - \frac{\partial^2 u}{\partial t^2} = 0, \quad 0 \le x \le 1$

Problem set-up such that the boundary condition at one extremity (x=0) is: $\forall t$,

$$\frac{\partial u}{\partial x}(0,t) = 0$$

 \Rightarrow general form of the solution: $u = \exp(\lambda t) (\exp(\lambda x) + \exp(-\lambda x))$

From the jump condition $P_m^{1/2}u - b = 0$ and the induction equation $\frac{\partial b}{\partial t} = -\frac{\partial u}{\partial x}$ (Bo,x enters the fluid) the boundary condition at the other extremity (x=1) is of mixed type: $\forall t$, $\frac{\partial u}{\partial x} = -P_m^{1/2}\frac{\partial u}{\partial t} = -\lambda P_m^{1/2}u$ $\exp(2\lambda) = \frac{1 - P_m^{1/2}}{1 + P_m^{1/2}}, \quad \lambda = \frac{1}{2}\left(\log\left[\frac{1 - P_m^{1/2}}{1 + P_m^{1/2}}\right] + 2n\pi i\right)$

log, principal branch (in the complex plane) of the logarithm.

Frequency jump from $P_m^{1/2} = 1^-$ to $P_m^{1/2} = 1^+$: $n\pi \to n\pi + \frac{\pi}{2}$



Reflection of an impulsive wave

Solution of the form f(t-x) + F(t+x)

At x=1
$$\frac{\partial u}{\partial x} = -P_m^{1/2} \frac{\partial u}{\partial t}$$

Reflected wave $F = \frac{1 - P_m^{1/2}}{1 + P_m^{1/2}} f$

Reflection coefficient:



Reflection at the equator

Comparison between 1D theory and 3D simulations

Mantle conductivity:

Reflection of an impulsive wave

Magnetic Prandtl number:



Dependence on the width of the incoming pulse d and apparent dispersion upon reflection

1D equations for torsional waves in the sphere with magnetic and/or viscous coupling

From the estimation of the magnetic field at the top of the mainstream (in the presence of a conducting mantle):

Braginsky, 1970

$$b_{\phi} = -Qs\zeta_G$$

$$\frac{\partial^2 \zeta_G}{\partial t^2} = \frac{1}{m} \frac{\partial}{\partial s} \left(m V_A^2 \frac{\partial \zeta_G}{\partial s} \right) - \frac{Q(\theta)}{h^2} \frac{\partial \zeta_G}{\partial t}$$
$$Q(\theta) = \sqrt{\frac{\mu_0}{\rho}} B_r(\theta) \int_{\text{mantle}} \sigma(r, \theta) dr$$

Plane wall prediction vs reduced (1D) modelling





Transmission, branching and reflection

